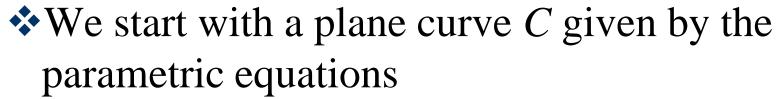
CHAPTER 13 VECTOR CALCULUS

LINE INTEGRALS

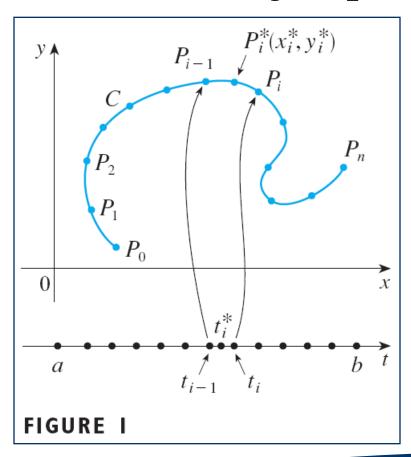


$$x = x(t)$$
 $y = y(t)$ $a \le t \le b$

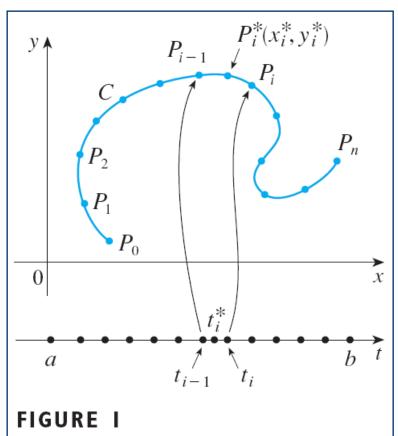
- Equivalently, C can be given by the vector equation $\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j}$.
- \bullet We assume that C is a smooth curve.
 - This means that \mathbf{r}' is continuous and $\mathbf{r}'(t) \neq \mathbf{0}$.
 - See Section 10.7

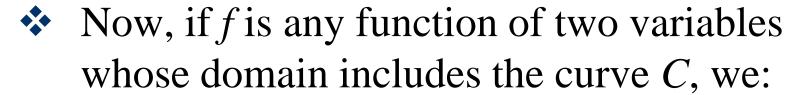
- Let's divide the parameter interval [a, b] into n subintervals $[t_{i-1}, t_i]$ of equal width.
- •• We let $x_i = x(t_i)$ and $y_i = y(t_i)$.

- *Then, the corresponding points $P_i(x_i, y_i)$ divide C into n subarcs with lengths $\Delta s_1, \Delta s_2, \ldots, \Delta s_n$.
- ❖See Figure 1.



- We choose any point $P_i^*(x_i^*, y_i^*)$ in the *i*th subarc.
 - This corresponds to a point t_i^* in $[t_{i-1}, t_i]$.





- 1. Evaluate f at the point (x_i^*, y_i^*) .
- 2. Multiply by the length Δs_i of the subarc.
- 3. Form the sum $\sum_{i=1}^{n} f(x_i^*, y_i^*) \Delta s_i$ which is similar to a Riemann sum.
- Then, we take the limit of these sums and make the following definition by analogy with a single integral.

Definition 2

If f is defined on a smooth curve C given by Equations 1, the line integral of f along C is:

$$\int_{C} f(x, y) ds = \lim_{\max \Delta s_{i} \to 0} \sum_{i=1}^{n} f(x_{i}^{*}, y_{i}^{*}) \Delta s_{i}$$

if this limit exists.

 \bullet In Section 9.2, we found that the length of C is:

$$L = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

• A similar type of argument can be used to show that, if *f* is a continuous function, then the limit in Definition 2 always exists.

Formula 3

Then, this formula can be used to evaluate the line integral.

$$\int_{C} f(x, y) ds$$

$$= \int_{a}^{b} f(x(t), y(t)) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

- ❖ The value of the line integral does not depend on the parametrization of the curve—provided the curve is traversed exactly once as t increases from a to b.
- $rightharpoonup^*$ If s(t) is the length of C between $\mathbf{r}(a)$ and $\mathbf{r}(t)$, then

$$\frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}$$

- ❖So, the way to remember Formula 3 is to express everything in terms of the parameter *t*:
 - Use the parametric equations to express x and y in terms of t and write ds as:

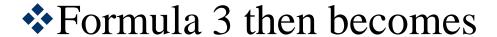
$$ds = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

In the special case where C is the line segment that joins (a, 0) to (b, 0), using x as the parameter, we can write the parametric equations of C as:

$$x = x$$

$$y = 0$$

$$a < x < b$$

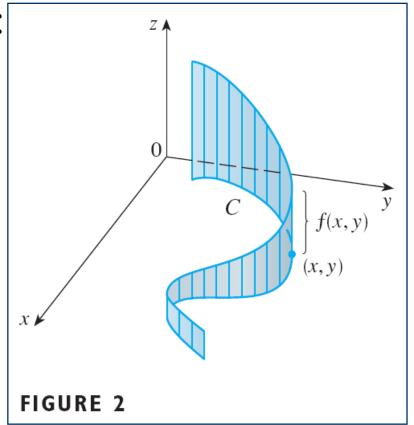


$$\int_{C} f(x, y) ds = \int_{a}^{b} f(x, 0) dx$$

- So, the line integral reduces to an ordinary single integral in this case.
- ❖ Just as for an ordinary single integral, we can interpret the line integral of a *positive function* as an area.

❖In fact, if $f(x, y) \ge 0$, $\int_C f(x, y) ds$ represents the area of one side of the "fence" or "curtain" shown in Figure 2, whose:

- Base is C.
- Height above the point (x, y) is f(x, y).



Example 1



$$\int_{C} (2 + x^{2}y) ds$$

where C is the upper half of the unit circle $x^2 + y^2 = 1$

SOLUTION

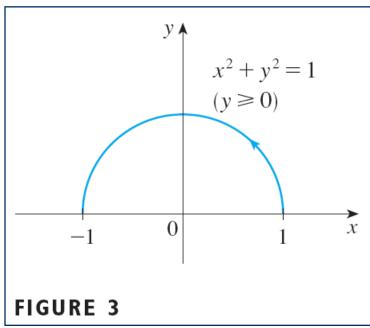
■ To use Formula 3, we first need parametric equations to represent *C*.

❖ Recall that the unit circle can be parametrized by means of the equations

$$x = \cos t$$
 $y = \sin t$

Also, the upper half of the circle is described by the parameter interval

$$0 \le t \le \pi$$



❖So, Formula 3 gives:

$$\int_{C} (2+x^{2}y) ds = \int_{0}^{\pi} (2+\cos^{2}t \sin t) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$

$$= \int_{0}^{\pi} (2+\cos^{2}t \sin t) \sqrt{\sin^{2}t + \cos^{2}t} dt$$

$$= \int_{0}^{\pi} (2+\cos^{2}t \sin t) dt$$

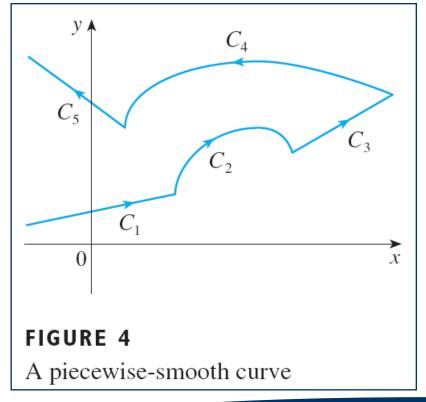
$$= \left[2t - \frac{\cos^{3}t}{3}\right]_{0}^{\pi} = 2\pi + \frac{2}{3}$$

PIECEWISE-SMOOTH CURVE



■ That is, C is a union of a finite number of smooth curves C_1 , C_2 , ..., C_n , where the initial point of C_{i+1}

is the terminal point of C_i .



Then, we define the integral of f along C as the sum of the integrals of f along each of the smooth pieces of C:

$$\int_{C} f(x, y) ds$$

$$= \int_{C_{1}} f(x, y) ds + \int_{C_{2}} f(x, y) ds + ... + \int_{C_{n}} f(x, y) ds$$

Example 2

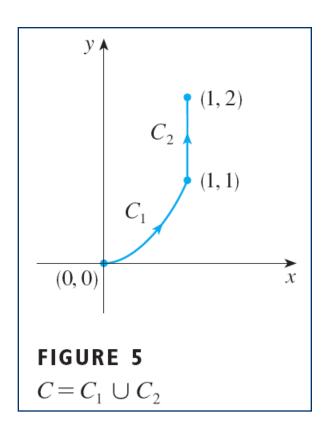


$$\int_C 2x \, ds$$

where C consists of the arc C_1 of the parabola $y = x^2$ from (0, 0) to (1, 1) followed by the vertical line segment C_2 from (1, 1) to (1, 2).

- The curve is shown in Figure 5.
- C_1 is the graph of a function of x.
 - So, we can choose *x* as the parameter.
 - Then, the equations for C_1 become:

$$x = x$$
 $y = x^2$ $0 \le x \le 1$





$$\int_{C_1} 2x \, ds = \int_0^1 2x \sqrt{\left(\frac{dx}{dx}\right)^2 + \left(\frac{dy}{dx}\right)^2} \, dx$$

$$= \int_0^1 2x \sqrt{1 + 4x^2} \, dx$$

$$= \frac{1}{4} \cdot \frac{2}{3} \left(1 + 4x^2\right)^{3/2} \Big]_0^1$$

$$= \frac{5\sqrt{5} - 1}{6}$$

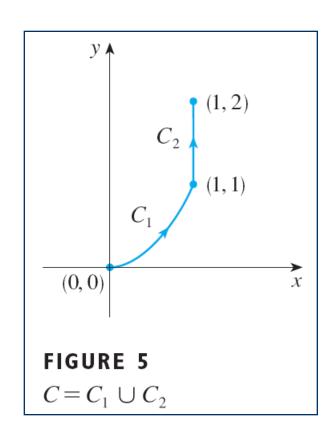
- \bullet On C_2 , we choose y as the parameter.
 - So, the equations of C_2 are

$$x = 1$$
 $y = 1$ $1 \le y \le 2$ and

$$\int_{C_2} 2x \, ds$$

$$= \int_1^2 2(1) \sqrt{\left(\frac{dx}{dy}\right)^2 + \left(\frac{dy}{dy}\right)^2} \, dy$$

$$= \int_1^2 2 \, dy = 2$$





$$\int_{C} 2x \, ds = \int_{C_{1}} 2x \, ds + \int_{C_{2}} 2x \, ds$$
$$= \frac{5\sqrt{5} - 1}{6} + 2$$



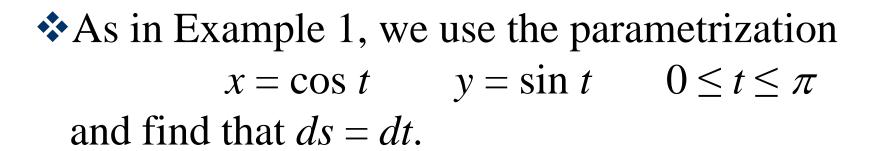
$$\int_{C} f(x, y) ds$$

depends on the physical interpretation of the function f.

• Suppose that $\rho(x, y)$ represents the linear density at a point (x, y) of a thin wire shaped like a curve C.

Example 3

- A wire takes the shape of the semicircle $x^2 + y^2 = 1$, $y \ge 0$, and is thicker near its base than near the top.
 - Find the center of mass of the wire if the linear density at any point is proportional to its distance from the line y = 1.





$$\rho(x, y) = k(1 - y)$$

where *k* is a constant.

❖So, the mass of the wire is:

$$m = \int_C k(1-y) ds = \int_0^{\pi} k(1-\sin t) dt$$
$$= k \left[t + \cos t\right]_0^{\pi}$$
$$= k \left(\pi - 2\right)$$

From Equations 4, we have:

$$\overline{y} = \frac{1}{m} \int_{C} y \, \rho(x, y) \, ds = \frac{1}{k(\pi - 2)} \int_{C} y \, k(1 - y) \, ds$$

$$= \frac{1}{\pi - 2} \int_{0}^{\pi} \left(\sin t - \sin^{2} t \right) dt$$

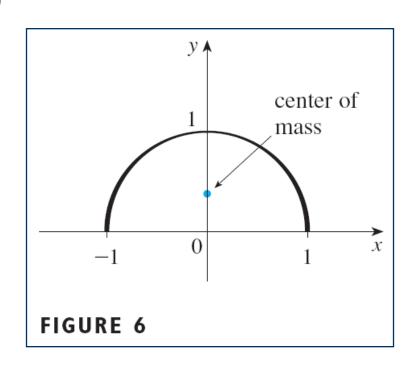
$$= \frac{1}{\pi - 2} \left[-\cos t - \frac{1}{2}t + \frac{1}{4}\sin 2t \right]_{0}^{\pi}$$

$$= \frac{4 - \pi}{2(\pi - 2)}$$

- **By** symmetry, we see that $\bar{x} = 0$.
- ❖So, the center of mass is:

$$\left(0, \frac{4-\pi}{2(\pi-2)}\right) \approx (0, 0.38)$$

See Figure 6.





$$\Delta x_i = x_i - x_{i-1}$$

$$\Delta y_i = y_i - y_{i-1}$$

❖ They are called the line integrals of f along C with respect to x and y:

$$\int_{C} f(x, y) dx = \lim_{\max \Delta x_{i} \to 0} \sum_{i=1}^{n} f(x_{i}^{*}, y_{i}^{*}) \Delta x_{i}$$

$$\int_{C} f(x, y) dy = \lim_{\max \Delta y_{j} \to 0} \sum_{i=1}^{n} f(x_{i}^{*}, y_{i}^{*}) \Delta y_{i}$$

ARC LENGTH

*When we want to distinguish the original line integral $\int_C f(x, y) ds$ from those in Equations 5 and 6, we call it the **line integral with respect** to arc length.

TERMS OF t

The following formulas say that line integrals with respect to *x* and *y* can also be evaluated by expressing everything in terms of *t*:

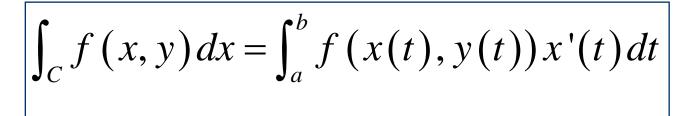
$$x = x(t)$$

$$y = y(t)$$

$$dx = x'(t) dt$$

$$dy = y'(t) dt$$

Formulas 7



$$\int_{C} f(x, y) dy = \int_{a}^{b} f(x(t), y(t)) y'(t) dt$$

ABBREVIATING

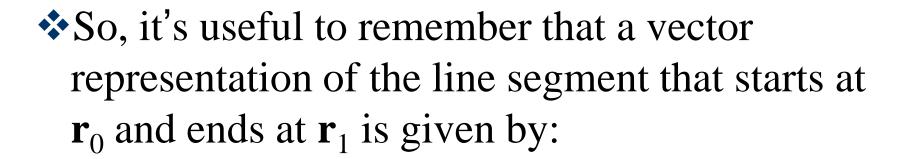
- ❖It frequently happens that line integrals with respect to *x* and *y* occur together.
 - When this happens, it's customary to abbreviate by writing

$$\int_{C} P(x, y) dx + \int_{C} Q(x, y) dy$$
$$= \int_{C} P(x, y) dx + Q(x, y) dy$$

LINE INTEGRALS

- When we are setting up a line integral, sometimes, the most difficult thing is to think of a parametric representation for a curve whose geometric description is given.
 - In particular, we often need to parametrize a line segment.

VECTOR REPRESENTATION



$$\mathbf{r}(t) = (1 - t)\mathbf{r}_0 + t \mathbf{r}_1 \quad 0 \le t \le 1$$

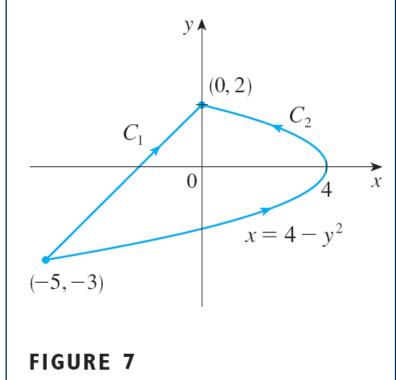
See Equation 4 in Section 10.5

Example 4

Evaluate $\int_C y^2 dx + x dy$ where (a) $C = C_1$ is the line segment from (-5, 3) to (0, 2) (b) $C = C_2$ is the arc of the parabola $x = 4 - y^2$ from (-5, 3) to

(0, 2).

❖See Figure 7.



Example 4(a) SOLUTION



$$x = 5t - 5$$
 $y = 5t - 3$ $0 \le t \le 1$

• Use Equation 8 with $\mathbf{r}_0 = \langle -5, 3 \rangle$ and $\mathbf{r}_1 = \langle 0, 2 \rangle$.

Example 4(a) SOLUTION

Then, dx = 5 dt, dy = 5 dt, and Formulas 7 give:

$$\int_{C_1} y^2 dx + x \, dy = \int_0^1 (5t - 3)^2 (5 \, dt) + (5t - 5)(5 \, dt)$$

$$= 5 \int_0^1 (25t^2 - 25t + 4) \, dt$$

$$= 5 \left[\frac{25t^3}{3} - \frac{25t^2}{2} + 4t \right]_0^1 = -\frac{5}{6}$$

Example 4(b) SOLUTION

- The parabola is given as a function of y.
- \diamond So, let's take y as the parameter and write C_2 as:

$$x = 4 - y^2$$
 $y = y$ $-3 \le y \le 2$

Example 4(b) SOLUTION

❖ Then, dx = -2y dy and, by Formulas 7, we have:

$$\int_{C_2} y^2 dx + x \, dy = \int_{-3}^2 y^2 (-2y) \, dy + (4 - y^2) \, dy$$
$$= \int_{-3}^2 (-2y^3 - y^2 + 4) \, dy$$
$$= \left[-\frac{y^4}{2} - \frac{y^3}{3} + 4y \right]_{-3}^2 = 40 \frac{5}{6}$$

ARC LENGTH

- Notice that we got different answers in parts a and b of Example 4 although the two curves had the same endpoints.
 - Thus, in general, the value of a line integral depends not just on the endpoints of the curve but also on the path.
 - However, see Section 13.3 for conditions under which it is independent of the path.

ARC LENGTH

- Notice also that the answers in Example 4 depend on the direction, or orientation, of the curve.
 - If $-C_1$ denotes the line segment from (0, 2) to (-5, 0)-3), you can verify, using the parametrization

$$x = -5t$$

$$x = -5t \qquad \qquad y = 2 - 5t$$

$$0 \le t \le 1$$

that

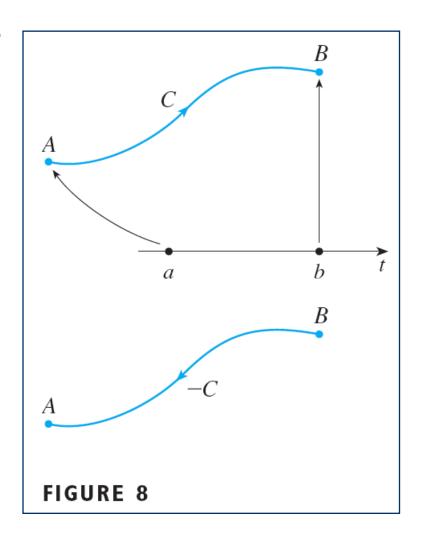
$$\int_{-C_1} y^2 dx + x \, dy = \frac{5}{6}$$



$$x = x(t), y = y(t), a \le t \le b$$

determines an **orientation** of a curve C, with the positive direction corresponding to increasing values of the parameter t.

- ❖For instance, See Figure 8
 - The initial point A corresponds to the parameter value.
 - The terminal point B corresponds to t = b.



❖ If −*C* denotes the curve consisting of the same points as *C* but with the opposite orientation (from initial point *B* to terminal point *A* in Figure 8), we have:

$$\int_{-C} f(x, y) dx = -\int_{C} f(x, y) dx$$
$$\int_{-C} f(x, y) dy = -\int_{C} f(x, y) dy$$

❖ However, if we integrate with respect to arc length, the value of the line integral does not change when we reverse the orientation of the curve:

$$\int_{-C} f(x, y) ds = \int_{C} f(x, y) ds$$

This is because Δs_i is always positive, whereas Δx_i and Δy_i change sign when we reverse the orientation of C.

 \bullet We now suppose that C is a smooth space curve given by the parametric equations

$$x = x(t)$$
 $y = y(t)$ $z = z(t)$ $a \le t \le b$

or by a vector equation

$$\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j} + z(t) \mathbf{k}$$

- Suppose *f* is a function of three variables that is continuous on some region containing *C*.
 - Then, we define the **line integral of** *f* **along** *C* (with respect to arc length) in a manner similar to that for plane curves:

$$\int_{C} f(x, y, z) ds = \lim_{\max \Delta s_{i} \to 0} \sum_{i=1}^{n} f(x_{i}^{*}, y_{i}^{*}, z_{i}^{*}) \Delta s_{i}$$

❖ We evaluate it using a formula similar to Formula 3:

$$\int_{C} f(x, y, z) ds$$

$$= \int_{a}^{b} f(x(t), y(t), z(t)) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2} + \left(\frac{dz}{dt}\right)^{2}} dt$$

Observe that the integrals in both Formulas 3 and 9 can be written in the more compact vector notation

$$\int_{a}^{b} f(\mathbf{r}(t)) |\mathbf{r}'(t)| dt$$



$$\int_C ds = \int_a^b |\mathbf{r}'(t)| dt = L$$

where L is the length of the curve C.

See Formula 3 in Section 10.8

- \bigstar Line integrals along C with respect to x, y, and z can also be defined.
 - For example,

$$\int_{C} f(x, y, z) dz = \lim_{\max \Delta z_{i} \to 0} \sum_{i=1}^{n} f(x_{i}^{*}, y_{i}^{*}, z_{i}^{*}) \Delta z_{i}$$
$$= \int_{a}^{b} f(x(t), y(t), z(t)) z'(t) dt$$

Thus, as with line integrals in the plane, we evaluate integrals of the form

$$\int_C P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz$$

by expressing everything (x, y, z, dx, dy, dz) in terms of the parameter t.

Example 5

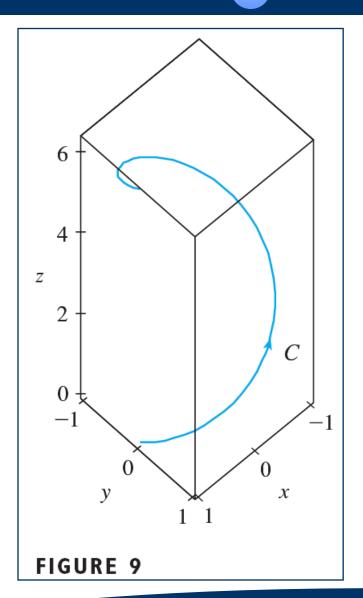
$$\star$$
Evaluate $\int_C y \sin z \, ds$

where *C* is the circular helix given by the equations

$$x = \cos t$$
$$y = \sin t$$
$$z = t$$

$$0 \le t \le 2\pi$$

See Figure 9.





$$\int_C y \sin z \, ds$$

$$= \int_0^{2\pi} (\sin t) \sin t \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt$$

$$= \int_0^{2\pi} \sin^2 t \sqrt{\sin^2 t + \cos^2 t + 1} \, dt$$

$$= \sqrt{2} \int_0^{2\pi} \frac{1}{2} (1 - \cos 2t) dt$$

$$=\frac{\sqrt{2}}{2}\left[t-\frac{1}{2}\sin 2t\right]_0^{2\pi}=\sqrt{2}\pi$$

Example 6

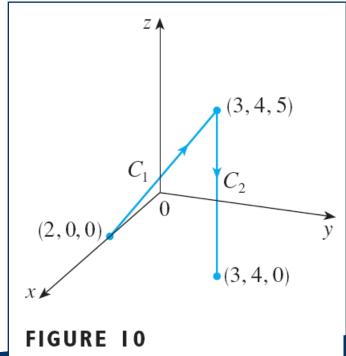


$$\int_C y \, dx + z \, dy + x \, dz$$
 where C consists of the line segment C_1 from (2, 0, 0) to (3, 4, 5), followed by the vertical line segment C_2 from (3, 4, 5) to (3, 4, 0).

- \bullet The curve C is shown in Figure 10.
 - Using Equation 8, we write C_1 as:

$$r(t) = (1 - t)\langle 2, 0, 0 \rangle + t \langle 3, 4, 5 \rangle$$

= $\langle 2 + t, 4t, 5t \rangle$



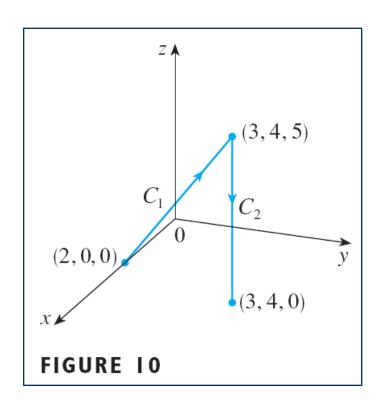
■ Alternatively, in parametric form, we write C_1 as:

$$x = 2 + t$$

$$y = 4t$$

$$z = 5t$$

$$0 \le t \le 1$$





$$\int_{C_1} y \, dx + z \, dy + x \, dz$$

$$= \int_0^1 (4t) \, dt + (5t) \, 4 \, dt + (2+t) \, 5 \, dt$$

$$= \int_0^1 (10 + 29t) \, dt$$

$$= 10t + 29 \frac{t^2}{2} \Big]_0^1 = 24.5$$

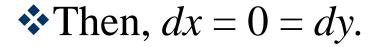


$$r(t) = (1 - t) \langle 3, 4, 5 \rangle + t \langle 3, 4, 0 \rangle$$

= $\langle 3, 4, 5 - 5t \rangle$

or

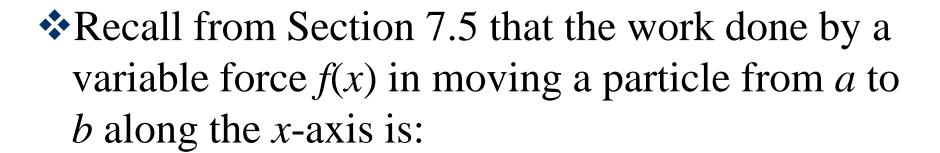
$$x = 3$$
 $y = 4$ $z = 5 - 5t$ $0 \le t \le 1$



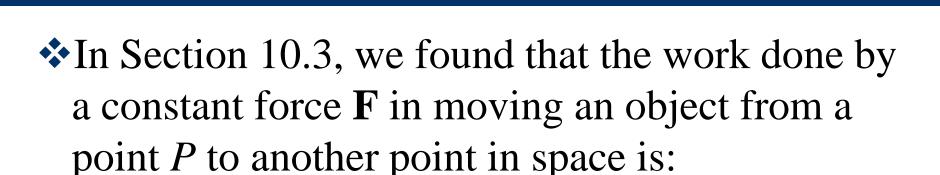
$$\int_{C_1} y \, dx + z \, dy + x \, dz = \int_0^1 3(-5) \, dt = -15$$

- **❖**So,
 - Adding the values of these integrals, we obtain:

$$\int_{C_1} y \, dx + z \, dy + x \, dz = 24.5 - 15 = 9.5$$



$$W = \int_{a}^{b} f(x) dx$$



$$W = \mathbf{F} \cdot \mathbf{D}$$

where $\mathbf{D} = \overrightarrow{PQ}$ is the displacement vector.



❖Now, suppose that

$$\mathbf{F} = P \, \mathbf{i} + Q \, \mathbf{j} + R \, \mathbf{k}$$

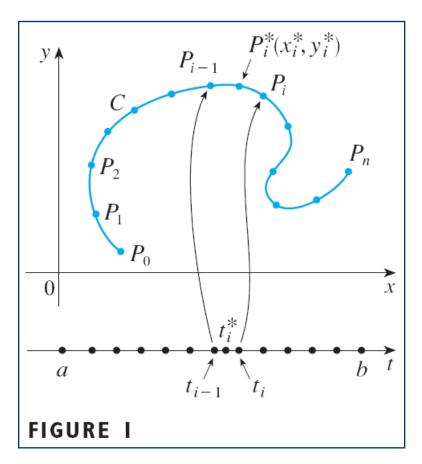
is a continuous force field on \mathbb{R}^3 , such as:

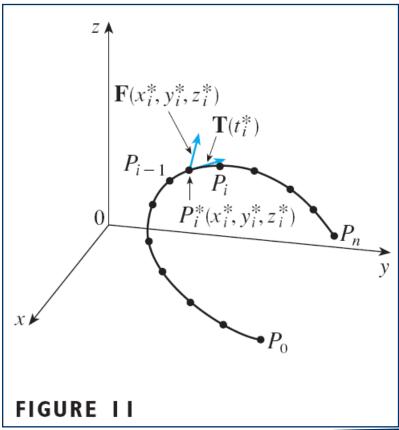
- The gravitational field of Example 4 in Section 13.1
- The electric force field of Example 5 in Section 13.1

- A force field on \mathbb{R}^3 could be regarded as a special case where R = 0 and P and Q depend only on x and y.
 - We wish to compute the work done by this force in moving a particle along a smooth curve *C*.

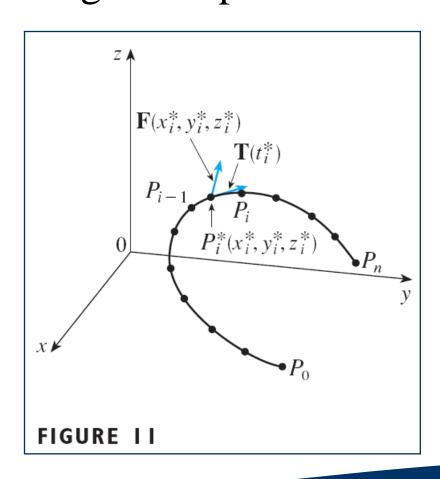
*We divide C into subarcs $P_{i-1}P_i$ with lengths Δs_i by dividing the parameter interval [a, b] into subintervals of equal width.

- ❖ Figure 1 shows the two-dimensional case.
- The second shows the three-dimensional one.



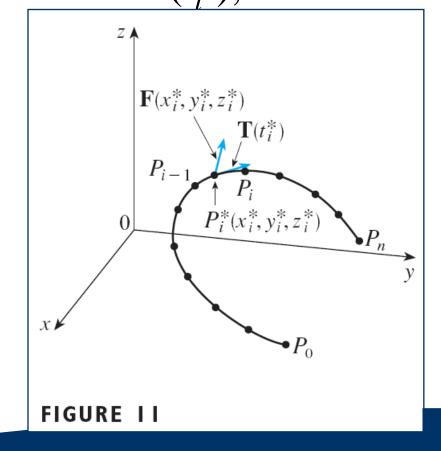


Choose a point $P_i^*(x_i^*, y_i^*, z_i^*)$ on the *i*th subarc corresponding to the parameter value t_i^* .



If Δs_i is small, then as the particle moves from P_{i-1} to P_i along the curve, it proceeds approximately in the direction of $\mathbf{T}(t_i^*)$, the unit

tangent vector at P_i^* .



LINE INTEGRALS OF VECTOR FIELDS

*Thus, the work done by the force \mathbf{F} in moving the particle P_{i-1} from to P_i is approximately

$$\mathbf{F}(x_i^*, y_i^*, z_i^*) \cdot [\Delta s_i \mathbf{T}(t_i^*)]$$

$$= [\mathbf{F}(x_i^*, y_i^*, z_i^*) \cdot \mathbf{T}(t_i^*)] \Delta s_i$$

❖ The total work done in moving the particle along *C* is approximately

$$\sum_{i=1}^{n} \left[\mathbf{F}(x_i^*, y_i^*, z_i^*) \cdot \mathbf{T}(x_i^*, y_i^*, z_i^*) \right] \Delta s_i$$

where T(x, y, z) is the unit tangent vector at the point (x, y, z) on C.

❖Intuitively, we see that these approximations ought to become better as *n* becomes larger.

❖Thus, we define the work W done by the force field F as the limit of the Riemann sums in Formula 11, namely,

$$W = \int_{C} \mathbf{F}(x, y, z) \cdot \mathbf{T}(x, y, z) ds = \int_{C} \mathbf{F} \cdot \mathbf{T} ds$$

• This says that work is the line integral with respect to arc length of the tangential component of the force.



$$\mathbf{r}(t) = x(t) \mathbf{i} + y(t) \mathbf{j} + z(t) \mathbf{k}$$

then

$$\mathbf{T}(t) = \mathbf{r}'(t)/|\mathbf{r}'(t)|$$

❖So, using Equation 9, we can rewrite Equation 12 in the form

$$W = \int_{a}^{b} \left[\mathbf{F}(\mathbf{r}(t)) \cdot \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|} \right] |\mathbf{r}'(t)| dt$$
$$= \int_{a}^{b} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$

- *This integral is often abbreviated as $\int_C \mathbf{F} \cdot d\mathbf{r}$ and occurs in other areas of physics as well.
 - Thus, we make the following definition for the line integral of any continuous vector field.

Definition 13

Let **F** be a continuous vector field defined on a smooth curve C given by a vector function $\mathbf{r}(t)$, $a \le t \le b$. Then, the **line integral of F along** C is:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{a}^{b} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_{C} \mathbf{F} \cdot \mathbf{T} ds$$

*When using Definition 13, remember $\mathbf{F}(\mathbf{r}(t))$ is just an abbreviation for

$$\mathbf{F}(x(t), y(t), z(t))$$

- So, we evaluate $\mathbf{F}(\mathbf{r}(t))$ simply by putting x = x(t), y = y(t), and z = z(t) in the expression for $\mathbf{F}(x, y, z)$.
- Notice also that we can formally write $d\mathbf{r} = \mathbf{r}'(t) dt$.

Example 7



$$\mathbf{F}(x, y) = x^2 \mathbf{i} - xy \mathbf{j}$$

in moving a particle along the quarter-circle

$$\mathbf{r}(t) = \cos t \, \mathbf{i} + \sin t \, \mathbf{j}, \quad 0 \le t \le \pi/2$$

Example 7 SOLUTION



$$\mathbf{F}(\mathbf{r}(t)) = \cos^2 t \, \mathbf{i} - \cos t \, \sin t \, \mathbf{j}$$

and

$$\mathbf{r}'(t) = -\sin t \, \mathbf{i} + \cos t \, \mathbf{j}$$

Example 7 SOLUTION

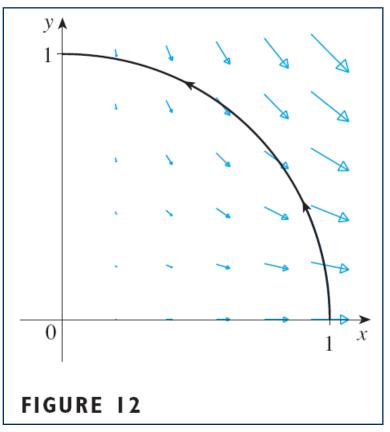
Therefore, the work done is:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{0}^{\pi/2} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$

$$= \int_{0}^{\pi/2} \left(-2\cos^{2}t \sin t \right) dt$$

$$= 2 \frac{\cos^{3}t}{3} \Big|_{0}^{\pi/2} = -\frac{2}{3}$$

- Figure 12 shows the force field and the curve in Example 7.
 - The work done is negative because the field impedes movement along the curve.



Note

Although $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C \mathbf{F} \cdot \mathbf{T} \, ds$ and integrals with respect to arc length are unchanged when orientation is reversed, it is still true that:

$$\int_{-C} \mathbf{F} \cdot d\mathbf{r} = -\int_{C} \mathbf{F} \cdot d\mathbf{r}$$

■ This is because the unit tangent vector \mathbf{T} is replaced by its negative when C is replaced by -C.

Example 8



$$\int_C \mathbf{F} \cdot d\mathbf{r}$$

where:

- $F(x, y, z) = xy \mathbf{i} + yz \mathbf{j} + zx \mathbf{k}$
- C is the twisted cubic given by

$$x = t \qquad y = t^2 \qquad z = t^3 \qquad 0 \le t \le 1$$

Example 8 SOLUTION



$$\mathbf{r}(t) = t \mathbf{i} + t^2 \mathbf{j} + t^3 \mathbf{k}$$

$$\mathbf{r}'(t) = \mathbf{i} + 2t \mathbf{j} + 3t^2 \mathbf{k}$$

$$\mathbf{F}(\mathbf{r}(t)) = t^3 \mathbf{i} + t^5 \mathbf{j} + t^4 \mathbf{k}$$

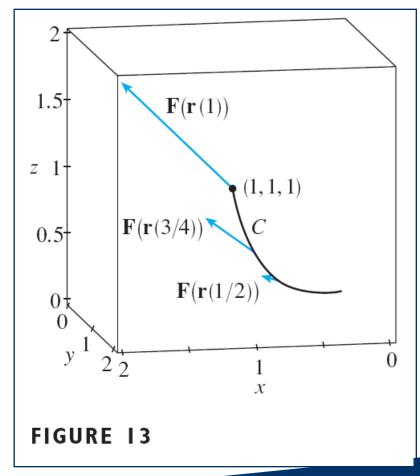
Thus,

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{0}^{1} \mathbf{F}(\mathbf{r}(t) \cdot \mathbf{r}'(t)) dt$$

$$= \int_{0}^{1} (t^{3} + 5t^{6}) dt = \frac{t^{4}}{4} + \frac{5t^{7}}{7} \Big]_{0}^{1} = \frac{27}{28}$$

❖ Figure 13 shows the twisted cubic in Example 8 and some typical vectors acting at three points

on C.



Finally, we note the connection between line integrals of vector fields and line integrals of scalar fields.

Suppose the vector field \mathbf{F} on \mathbb{R}^3 is given in component form by:

$$\mathbf{F} = P \mathbf{i} + Q \mathbf{j} + R \mathbf{k}$$

■ We use Definition 13 to compute its line integral along *C*, as follows.

$$\int_{C} \mathbf{F} \cdot d\mathbf{r}$$

$$= \int_{a}^{b} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$$

$$= \int_{a}^{b} (P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}) \cdot (x'(t)\mathbf{i} + y'(t)\mathbf{j} + z'(t)\mathbf{k}) dt$$

$$= \int_{a}^{b} \begin{bmatrix} P(x(t), y(t), z(t))x'(t) \\ +Q(x(t), y(t), z(t))y'(t) \\ +R(x(t), y(t), z(t))z'(t) \end{bmatrix}$$

- ❖ However, that last integral is precisely the line integral in Formula 10.
- **❖**Hence, we have:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{C} P \, dx + Q \, dy + R \, dz$$
where $\mathbf{F} = P \, \mathbf{i} + Q \, \mathbf{j} + R \, \mathbf{k}$



$$\int_C y \, dx + z \, dy + x \, dz$$

in Example 6 could be expressed as

$$\int_C \mathbf{F} \cdot d\mathbf{r}$$

where

$$\mathbf{F}(x, y, z) = y \mathbf{i} + z \mathbf{j} + x \mathbf{k}$$